

ABOUT THE NOETHER'S THEOREM FOR FRACTIONAL
LAGRANGIAN SYSTEMS AND A GENERALIZATION OF THE
CLASSICAL JOST METHOD OF PROOF

by

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Lagrangian $L : [a, b] \times \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$, $L(t, x, w, v)$,

$$\mathcal{L}_{\alpha, [a, b]}(x) = \int_a^b L(t, x(t), {}_c D_{a+}^{\alpha} x(t)) dt.$$

fractional Euler-Lagrange equation:

$$D_{b-}^{\alpha} \left(\frac{\partial L}{\partial v}(t, x(t), {}_c D_{a+}^{\alpha} x(t)) \right) + \frac{\partial L}{\partial x}(t, x(t), {}_c D_{a+}^{\alpha} x(t)) = 0,$$

one parameter group of diffeomorphisms with no transformation in time

$$\phi_s : \mathbb{R}^n \mapsto \mathbb{R}^n, s \in \mathbb{R}$$

$$\int_{t_a}^{t_b} L(t, x(t), {}_c D_{a+}^\alpha x(t)) dt = \int_{t_a}^{t_b} L(t, \phi_s(x)(t), {}_c D_{a+}^\alpha (\phi_s(x))(t)) dt,$$

where $[t_a, t_b] \in [a, b]$

$$\frac{\partial L}{\partial v}(\star) \cdot {}_c D_{a+}^\alpha \left(\frac{d}{ds} (\phi_s(x)) \Big|_{s=0} \right) - D_{b-}^\alpha \left(\frac{\partial L}{\partial v}(\star) \right) \cdot \frac{d}{ds} (\phi_s(x)) \Big|_{s=0} = 0,$$

where $(\star) = (t, x(t), {}_c D_{a+}^\alpha x(t))$.

$$\alpha = 1$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial v}(t, x(t), \dot{x}(t)) \cdot \frac{d}{ds} \phi_s(x) \Big|_{s=0} \right) = 0$$

What about transformations also changing time ?

projectable or fiber-preserving

$$\begin{aligned} \phi_s : [a, b] \times \mathbb{R}^n &\longrightarrow \mathbb{R} \times \mathbb{R}^n \\ (t, x) &\longrightarrow (\varphi_s^0(t), \varphi_s^1(x)), \end{aligned}$$

In the classical case :

$$I(\tau, (t, x), (w, v)) = \frac{\partial L}{\partial v}(t, x, v) \cdot \frac{d\varphi_s^1(x)}{ds} \Big|_{s=0} + \left(L(t, x, v) - v \frac{\partial L}{\partial v}(t, x, v) \right) \frac{\varphi_s^0(x)}{ds} \Big|_{s=0} .$$

Proof ?

J. Jost and X. Li-Jost. *Calculus of Variations*. Cambridge Studies in Advanced Mathematics. Cambridge University Press, 1998.

P. J. Olver, *Applications of Lie groups to differential equations*, 2d edition, Graduate Textes in Mathematics, Springer-Verlag, 1993.

Step 1- rewrite the invariance condition in order to have constant interval

$$\tau = \varphi_s^0(t),$$

$$\int_a^b L \left(t, x(t), \frac{dx(t)}{dt} \right) dt = \int_a^b L \left(\varphi_s^0(t), (\varphi_s^1 \circ x)(t), \frac{d}{dt} (\varphi_s^1 \circ x) (t) \frac{1}{\frac{d\varphi_s^0(t)}{dt}} \right) \frac{d\varphi_s^0(t)}{dt} dt.$$

Step 2 – introduce the extended Lagrangian

the *extended Lagrangian* defined by

$$\tilde{L}(\tau, (t, x), (w, v)) := L\left(t, x, \frac{v}{w}\right) \cdot w,$$

$$t(\tau) := \tau,$$

$$\tilde{L}(\tau, t(\tau), x(\tau), \dot{t}(\tau), \dot{x}(\tau)) = L(\tau, x(\tau), \dot{x}(\tau)).$$

$$\int_a^b \tilde{L}(\tau, t(\tau), x(\tau), \dot{t}(\tau), \dot{x}(\tau)) d\tau = \int_a^b L\left(\tau, \phi_s(t(\tau), x(\tau)), \frac{d}{dt}(\phi_s(t(\tau), x(\tau)))\right) d\tau.$$

Apply the Noether's theorem on the case of transformations without changing time

Step 3- do not forget to verify that the solutions of the Euler-Lagrange Equation for L are solutions for the extended Lagrangian

$$\frac{d}{d\tau} \left[\frac{\partial L}{\partial v} (\star_\tau) \right] = \frac{\partial L}{\partial x} (\star_\tau)$$

$$\frac{d}{d\tau} L(\star_\tau) = \frac{\partial L}{\partial t} (\star_\tau) + \frac{d}{d\tau} \left(\frac{dx(\tau)}{d\tau} \frac{\partial L}{\partial v} (\star_\tau) \right),$$

Frederico G.S.F., Torres D.F.M., *A formulation of Noether's theorem for fractional problems of the calculus of variations*, J. Math. Anal. Appl. 334 (2007) 834-846.

Frederico G.S.F., Torres D.F.M., *Fractional Noether's theorem in the Riesz-Caputo sense*, Applied Mathematics and Computation, Volume 217, Issue 3, 1 October 2010, Pages 1023-1033.

R. A. C. Ferreira, A. B. Malinowska, *A counterexample to Frederico and Torres's fractional Noether-type theorem*, J. Math. Anal. Appl., Volume 429, Issue 2, 15 September 2015, Pages 1370-1373.

Why the proof presented by Frederico and Torres is wrong ?

Step 0 – variational symmetries

Definition 3 (Variational symmetries). — The local group of transformation ϕ_s is a variational symmetry group of the functional (8) if whenever $I = [t_a, t_b]$ is a subinterval of $[a, b]$ and x is a smooth function defined over I such that its transform under ϕ_s denoted by \tilde{x} is defined over $\tilde{I} = [\mu_a, \mu_b]$ which is a subset of $\phi_s^0([a, b]) = [\tau_a, \tau_b]$, then

$$(20) \quad \mathcal{L}_{\alpha, a, I}(x) = \mathcal{L}_{\alpha, \tau(a), \tilde{I}}(\tilde{x}).$$

$$\int_{t_a}^{t_b} L(t, x(t), {}_c D_{a+}^{\alpha} x(t)) dt = \int_{\mu_a}^{\mu_b} L(\tau, \varphi_s^1 \circ x \circ (\varphi_s^0)^{-1}(\tau), {}_c D_{\tau_a+}^{\alpha} (\varphi_s^1 \circ x \circ (\varphi_s^0)^{-1}(\tau))) d\tau.$$

Frederico-Torres definition :

$$\int_{t_a}^{t_b} L(t, x(t), {}_c D_{a+}^{\alpha} x(t)) dt = \int_{\tau_a}^{\tau_b} L(\tau, \varphi_s^1 \circ x \circ (\varphi_s^0)^{-1}(\tau), {}_c D_{a+}^{\alpha} (\varphi_s^1 \circ x \circ (\varphi_s^0)^{-1}(\tau))) d\tau.$$

Localisation condition : $\phi_s^0(a) = a$ for all $s \in \mathbb{R}$.

Noether's theorem for fractional Lagrangian systems

$$\frac{d\phi_s^0}{dt} = K(s), \quad K(0) = 1$$

$$X = \zeta(t) \frac{\partial}{\partial t} + \xi(x) \frac{\partial}{\partial x},$$

$$I(x) = L(\star) \cdot \zeta + \int_a^t \left[-[\partial_x L(\star)] \cdot (\dot{x}\zeta - \xi) - \partial_v L(\star) \cdot \left(\zeta \cdot D_{a+}^{\alpha}[\dot{x}] + \dot{\zeta} \cdot D_{a+}^{\alpha}[x] - D_{a+}^{\alpha}(\xi) \right) \right] dt,$$

Step 1 – extended lagrangian

$${}_c D_{\tau_{a+}}^{\alpha} (\varphi_s^1 \circ x \circ (\varphi_s^0)^{-1})(\tau) \quad ?$$

Definition 4 (Admissible groups). — A local group of transformations $\{\phi_s = (\phi_s^0, \phi_s^1)\}_{s \in \mathbb{R}}$ is said to be admissible, if for all $s \in \mathbb{R}$, ϕ_s^0 is an affine function of t of the form

$$(51) \quad \phi_s^0(t) = e^{\lambda s} t + \beta(s),$$

with $\beta(s)$ satisfying $\beta(s + s') = e^{\lambda s} \beta(s') + \beta(s)$ for all $s, s' \in \mathbb{R}$ and $\beta(0) = 0$.

$${}_c D_{\phi_s^0(a)+}^{\alpha} (y \circ (\phi_s^0)^{-1})(\tau) = {}_c D_{a+}^{\alpha} (y)(t) \frac{1}{\left(\frac{d\phi_s^0}{dt}\right)^{\alpha}}.$$

$$\int_{t_a}^{t_b} L(t, x(t), {}_c D_{a+}^\alpha x(t)) dt = \int_{t_a}^{t_b} L\left(\varphi_s^0(t), \varphi_s^1 \circ x(t), {}_c D_{a+}^\alpha(\varphi_s^1 \circ x)(t) \frac{1}{\left(\frac{d\varphi_s^0}{dt}\right)^\alpha}\right) \frac{d\varphi_s^0(t)}{dt} dt.$$

$$\tilde{L}_\alpha(\tau, (t, x), (w, v)) := L\left(t, x, \frac{v}{w^\alpha}\right) \cdot w.$$

$$\begin{aligned} \tilde{\mathcal{L}}_{\alpha, [a, b]}(t, x) &= \int_a^b \tilde{L}\left(t(\tau), x(t(\tau)), \frac{dt(\tau)}{d\tau}, {}_c D_{a+}^\alpha x(t(\tau))\right) d\tau \\ &= \int_a^b \tilde{L}(t, x, w, v) d\tau. \end{aligned}$$

Step 2 - invariance

$$\tilde{\mathcal{L}}_{\alpha,[a,b]}(t, \mathbf{x}) = \tilde{\mathcal{L}}_{\alpha,[a,b]}(\phi_s(t, \mathbf{x})) = \tilde{\mathcal{L}}_{\alpha,[a,b]}(\varphi_s^0(t), \varphi_s^1(\mathbf{x})),$$

Invariance criterion

Lemma 9 (Infinitesimal invariance criterion). — *If the Lagrangian function $\tilde{\mathcal{L}}$ is invariant under the one parameter group $\{\phi_s = (\phi_s^0, \phi_s^1)\}_{s \in \mathbb{R}}$ then we have*

$$(68) \quad \partial_t \tilde{L} \cdot \frac{d\phi_s^0}{ds} \Big|_{s=0} + \partial_x \tilde{L} \cdot \frac{d\phi_s^1}{ds} \Big|_{s=0} + \partial_w \tilde{L} \cdot \frac{d}{dt} \left(\frac{d\phi_s^0}{ds} \Big|_{s=0} \right) + \partial_v \tilde{L} \cdot D_{a+}^\alpha \left(\frac{d\phi_s^1}{ds} \Big|_{s=0} \right) = 0$$

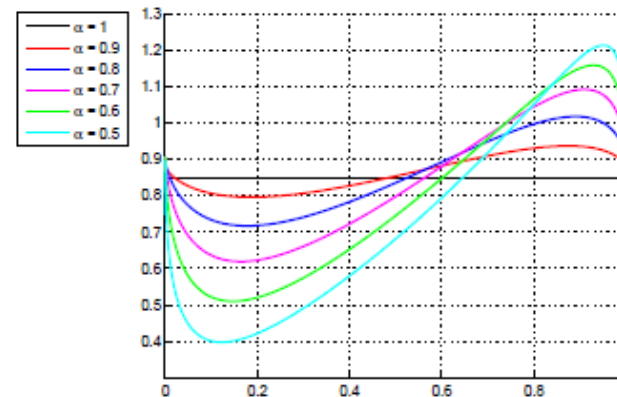
Step 3 – check that the solution of EL are solutions of the Extended EL

Not true in this case !

$$(CE_\alpha) \quad \frac{\partial L}{\partial t}(\star_\tau) - \frac{d}{d\tau} \left(L(\star_\tau) - {}_c D_{a+}^\alpha x(\tau) \cdot \frac{\partial L}{\partial v}(\star_\tau) \right) = 0,$$

$$L : \begin{array}{l} [0, 1] \times \mathbb{R}^2 \times \mathbb{R}^2 \longrightarrow \mathbb{R} \\ (t, x, v) \longrightarrow \frac{1}{2} (\|x\|^2 + \|v\|^2), \end{array}$$

$$Q_\alpha(x) := \frac{1}{2} (\|x\|^2 - \|v\|^2) = \text{const.}$$



Lemma 10. — Suppose $G = \{\phi_s\}_{s \in \mathbb{R}}$ is a one parameter group of symmetries of the variational problem $\mathcal{L}_{\alpha, [a, b]}(x) = \int_a^b L(t, x(t), {}_c D_{a+}^\alpha x(t)) dt$ satisfying the chain rule property. Let

$$(69) \quad X = \zeta(t) \frac{\partial}{\partial t} + \xi(x) \frac{\partial}{\partial x},$$

be the infinitesimal generator of G . Then, we have:

$$(70) \quad \partial_t L \cdot \zeta + \partial_x L \cdot \xi + L \cdot \dot{\zeta} + \partial_v L \cdot \left(-D_{a+}^\alpha x \cdot \dot{\zeta} + D_{a+}^\alpha(\xi) \right) = 0.$$

$$\frac{d}{dt} (L(\star)) = \partial_t L(\star) + \partial_x L(\star) \cdot \dot{x} + \partial_v L(\star) \cdot D_{a+}^\alpha[x],$$

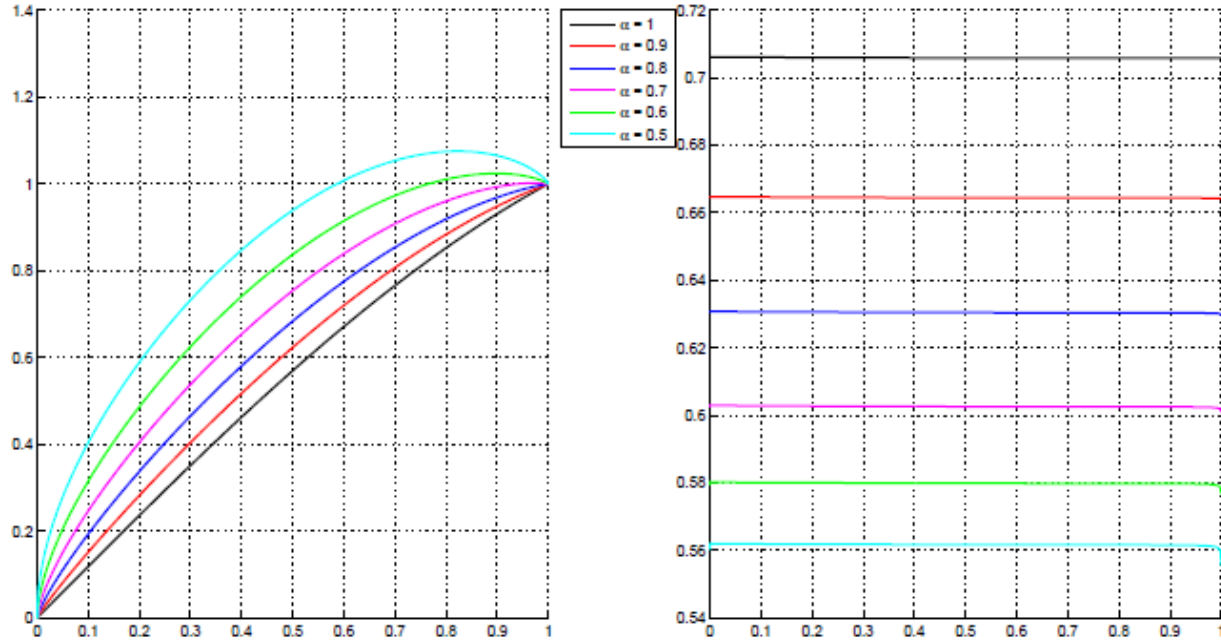
$$I(x) = L(\star) \cdot \zeta + \int_a^t \left[D_{b-}^\alpha [\partial_v L(\star)] \cdot (\dot{x}\zeta - \xi) - \partial_v L(\star) \cdot \left(\zeta \cdot D_{a+}^\alpha[\dot{x}] + \dot{\zeta} \cdot D_{a+}^\alpha[x] - D_{a+}^\alpha(\xi) \right) \right] dt.$$

T. T. Atanackovic, S. Konjik, S. Pilipovic, S. Simic, *Variational problems with fractional derivatives: invariance conditions and Nöther's theorem*, *Nonlinear Analysis* 71 (2009) 1504-1517.

$$L = \frac{1}{2} ({}_0D_t^\alpha u)^2 - \omega^2 \frac{1}{2} u^2,$$

$$u(0) = 0 \text{ and } u'(0) = 1.$$

$$\frac{1}{2} ({}_0D_t^\alpha u)^2 - \omega^2 \frac{1}{2} u^2 + \int_0^t (-{}_0D_s^\alpha u' \cdot {}_0D_s^\alpha u + u' \cdot {}_sD_1^\alpha ({}_0D_s^\alpha u)) ds = \text{const.}$$



The problem just identified....also in other proofs in different contex...
time scale, other fractional calculus, etc

Z. Bartosiewicz and D.F.M. Torres. Noether's theorem on time scales. *Journal of Mathematical Analysis and Applications*, 342(2):1220–1226, 2008.